

# Ocean rogue waves and the NLS equation

# Christian Kharif

Institut de Recherche sur les Phénomènes Hors Equilibre (IRPHE)

Ecole Centrale Marseille

# Observation of huge waves



Photo of a huge wave event



Photo of a huge wave event

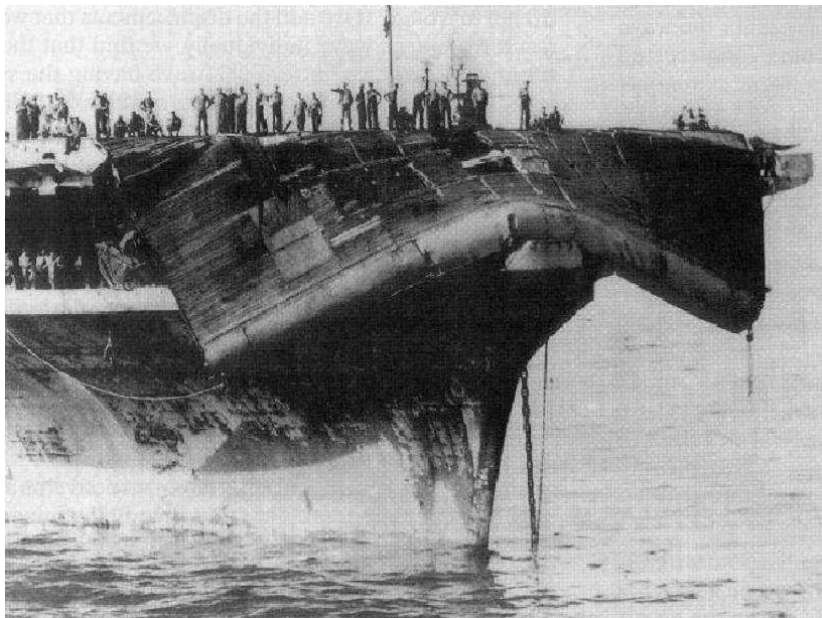


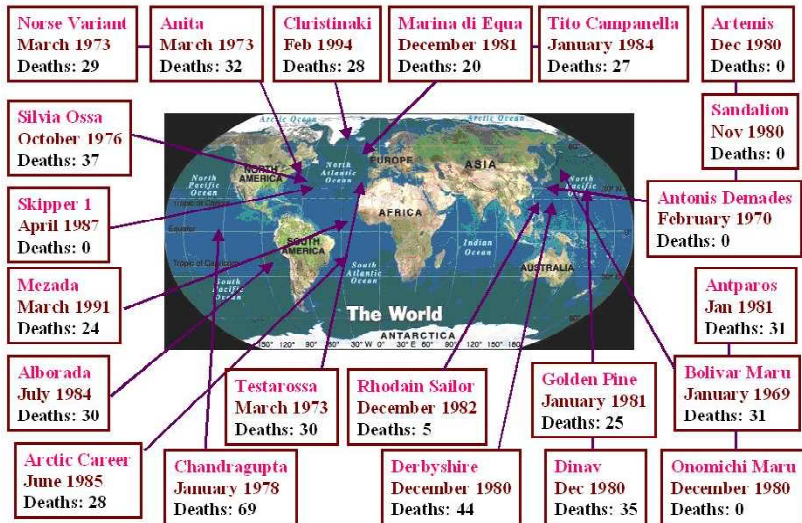
Photo of a huge wave event





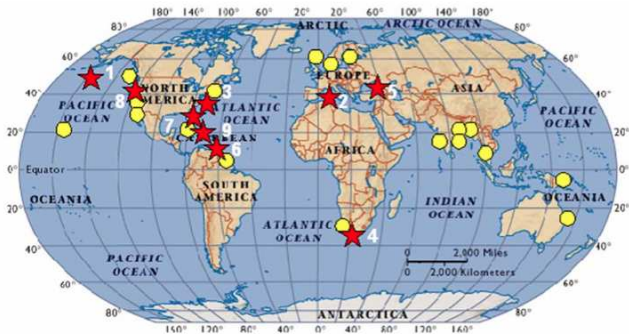




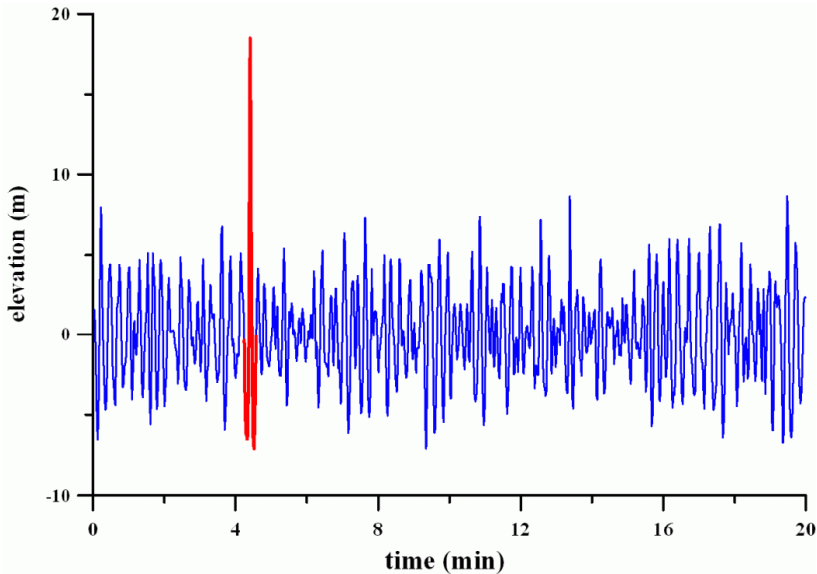


Super tanker collisions with freak waves (1968-1994).

## Rogue waves in 2005 (Didenkulova *et al*, 2006)



**Fig. 1.** Events selected as true freak waves are marked by red stars (1 – „Explorer”, 2 – “Grand Voyager”, 3 – “Norwegian Dawn”, 4 – Kalk Bay, 5 – Blue Bay, 6 – Maracas Beach, 7 – Blake de Pastino, 8 – Port Orford, 9 – Petit Havre); yellow circles mark all other reported cases when abnormally large waves were observed.



- ▶ Time record of the New Year Wave in the North Sea ( $H_{freak} = 25.3m$ ,  $\eta_{crest} = 18.5m$ ,  $H_s = 11.9m$ )

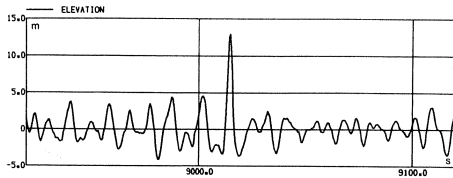


Figure 2. Freak wave A recorded on the 24th November, 1981 at the Gorm Field in the Danish Sector of the North Sea.

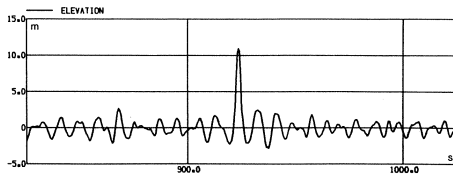


Figure 3. Freak wave B recorded on the 17th November, 1984 at the Gorm Field in the Danish Sector of the North Sea.

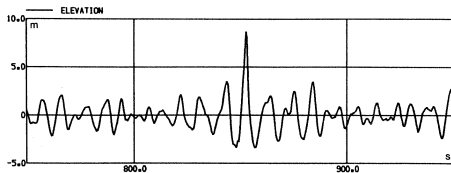


Figure 4. Freak wave C recorded on the 27th November, 1984 at the Gorm Field in the Danish Sector of the North Sea.

## Ferry collisions with rogue waves near the French coast

- ▶ The Pont Aven ( $L = 597 \text{ ft}$ ) hit a rogue wave ( $\approx 15 \text{ m}$ ) during the night 21-22 May 2006.
- ▶ The Louis Majesty ( $L = 207 \text{ m}$ ) hit a rogue wave ( $\approx 17 \text{ m}$ ) on 3 March 2010 and two passengers were killed.
- ▶ The Jean Nicoli ( $L = 200 \text{ m}$ ) hit a rogue wave ( $\approx 20 \text{ m}$ ) on 6 March 2017.

# Physical mechanisms of rogue wave generation

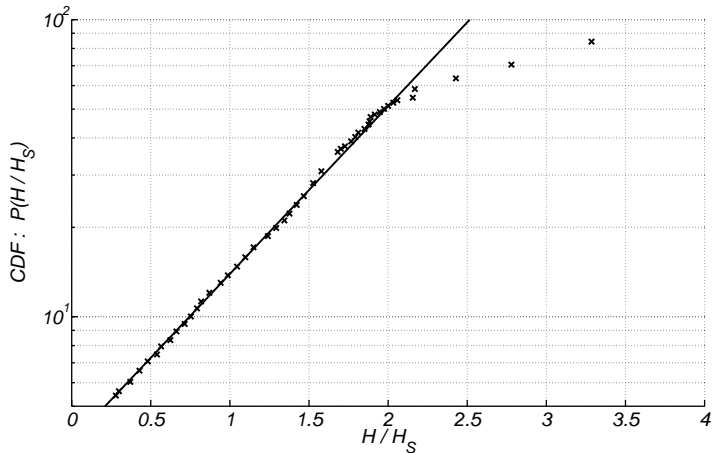
- ▶ Wave-current interactions
- ▶ Geometrical or spatial focusing
- ▶ spatio-temporal focusing or dispersive focusing
- ▶ **modulational instability (resonant four-wave interaction)**
- ▶ crossing seas
- ▶ soliton collision
- ▶ etc.



- ▶ Mathematically, a rogue wave of height  $H_f$  satisfies

$$H_f > 2H_s$$

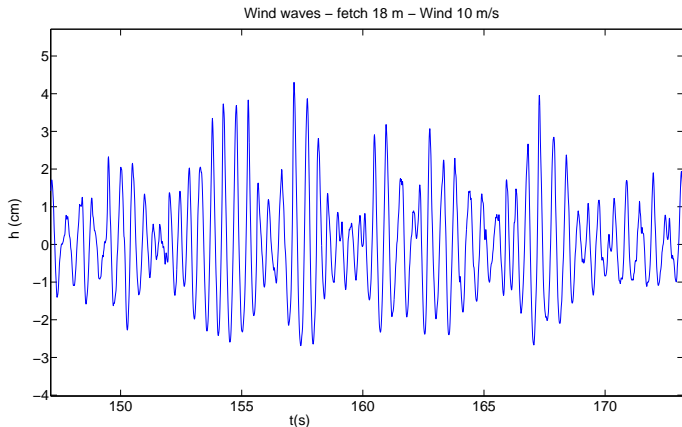
- ▶  $H_f$  is more than twice the significant height  $H_s$  or 8 times the rms of the surface elevation
- ▶ Waves with larger heights than expected based on the Rayleigh distribution (abnormal waves)
- ▶ The above definition was proposed by Soren Peter Kjelsen in 1989 during the Workshop on Water Wave Kinematics, Molde (Norway)
- ▶ Water Wave Kinematics, Nato ASI series, eds. A.Torum & O.T. Gudmestad, 1990



Cumulative distribution function (%) as a function of normalized wave height  $H/H_s$  (from Sand *et al*, 1989) corresponding to North Sea data during stormy weather

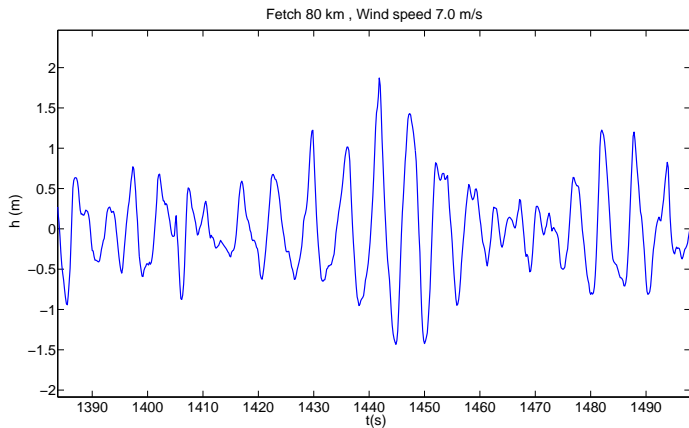
# Modulated water waves without and with the presence of a shear current

# Wind waves in the Large Air-Sea Interaction Facility (LASIF)



Fetch: 18 m and wind speed:  $10 \text{ m} \cdot \text{s}^{-1}$  from (H. Branger)

## Wind waves in open field



Fetch: 80 km and wind speed:  $7 \text{ m} \cdot \text{s}^{-1}$  (from H. Branger)

- ▶ This strong group structure of the wave field or modulational aspect of the surface elevation is due to resonant 4-wave interactions
  
- ▶ An elegant analytical method to study nonlinear modulational processes is the **nonlinear Schrödinger equation**

## The nonlinear Schrödinger equation (NLS equation)

- ▶ governs the spatio-temporal evolution of the complex envelope of the free surface of weakly nonlinear and dispersive water waves
- ▶ is a universal equation that can be derived from the nonlinear water wave equations using the method of multiple scales
- ▶ was first derived within the framework of water waves by Benney & Newell (1967)

- ▶ Let us consider a weakly nonlinear modulated wave train propagating on **finite depth** at the free surface of a **shear current of constant vorticity**

$$\eta(x, t) = \frac{1}{2}(\epsilon a(\xi, \tau) \exp[i(kx - \omega t)] + c.c) + \mathcal{O}(\epsilon^2)$$

$$\text{where } \xi = \epsilon(x - c_g t) \text{ and } \tau = \epsilon^2 t.$$

- ▶ Starting from the nonlinear water wave equations and using the **method of multiple scales**, the evolution of the complex envelope is governed by the NLS equation

$$i(a_\tau + c_g a_\xi) + L a_{\xi\xi} + N |a|^2 a = 0$$



$$L = \frac{\omega}{k^2 \sigma (2 + X)} \{ \mu (1 - \sigma^2) [1 - \mu \sigma + (1 - r) X] - \sigma r^2 \}$$

$$N = - \frac{\omega k^2 (U + VW)}{2(1 + X)(2 + X)\sigma^4}$$

$$U = 9 - 12\sigma^2 + 13\sigma^4 - 2\sigma^6 + (27 - 18\sigma^2 + 15\sigma^4)X + (33 - 3\sigma^2 + 4\sigma^4)X^2 + (21 + 5\sigma^2)X^3 + (7 + 2\sigma^2)X^4 + X^5$$

$$V = (1 + X)^2 (1 + r + \mu \bar{\Omega}) + 1 + X - r\sigma^2 - \mu\sigma X$$

$$W = 2\sigma^3 \frac{(1 + X)(2 + X) + r(1 - \sigma^2)}{\sigma r (r + \mu \bar{\Omega}) - \mu(1 + X)}$$

where  $\mu = kh$ ,  $\sigma = \tanh(\mu)$ ,  $r = c_g/c_p$ ,  $\bar{\Omega} = \Omega/\omega(\Omega)$  and  $X = \sigma \bar{\Omega}$

In deep water without shear current the coefficients reads

$$L = -\frac{\omega}{8k^2} \quad \text{and} \quad N = -\frac{1}{2}\omega k^2$$

- ▶ The vor-NLS equation admits the following Stokes' wave solution

$$a = a_0 \exp(iNa_0^2\tau)$$

- ▶ Perturbation

$$a = a_0(1 + \delta a) \exp[i(\delta\omega + Na_0^2\tau)]$$

with

$$\delta a = (\delta a)_0 \exp[i(l\xi - \lambda\tau)]$$

$$\delta\omega = (\delta\omega)_0 \exp[i(l\xi - \lambda\tau)]$$

- ▶ Condition of linear instability with respect to sideband perturbations

$$LN > 0$$

$$\text{Let } L = L_1\omega/k^2 \text{ and } N = N_1\omega k^2$$

- ▶ Modulational instability occurs for perturbations whose wavenumber  $l$  satisfies

$$-\sqrt{2\frac{N_1}{L_1}}ka_0 < \frac{l}{k} < \sqrt{2\frac{N_1}{L_1}}ka_0$$

- ▶ The growth rate of instability is

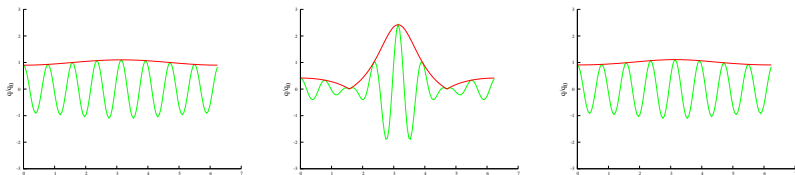
$$\gamma = \frac{l\omega}{k^2} \sqrt{2N_1L_1k^4a_0^2 - l^2L_1^2}$$

- ▶ Maximal growth rate

$$\gamma_{\max} = -N_1\omega(a_0k)^2 \quad \text{for} \quad l_{\max} = \sqrt{N_1/L_1}a_0k^2$$

- ▶ For  $\Omega < -2\sqrt{\frac{gk}{3\sigma}} \Rightarrow$  **no BF instability**

## Nonlinear evolution of BF instability

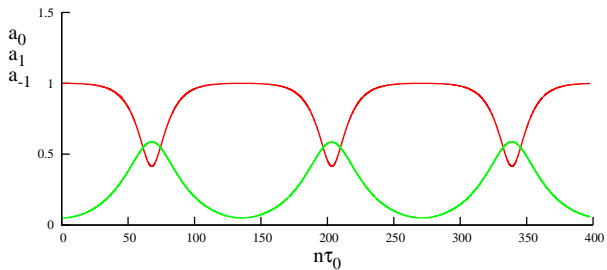


Envelope of surface elevation of a Stokes wave train of initial steepness  $|A_0|k = 0.125$  amplified by its most unstable perturbation (FPU recurrence)

$$i \frac{\partial q}{\partial T} + \frac{\partial^2 q}{\partial X^2} + 2 |q|^2 q = 0$$

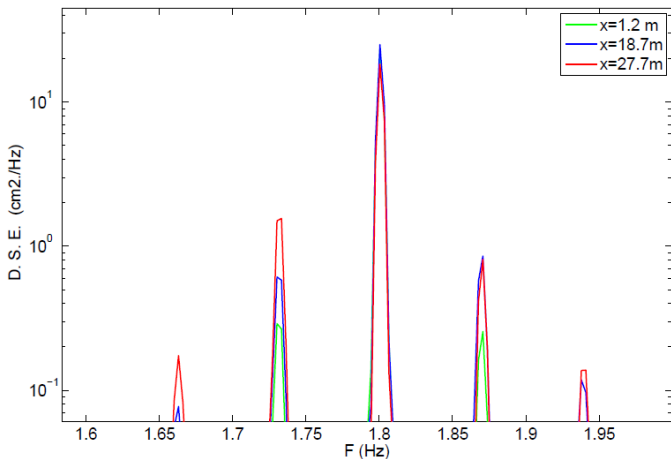
with

$$T = \frac{1}{2} \omega \tau, \quad X = 2k\xi, \quad q = \frac{1}{\sqrt{2}} k A^*$$



Temporal evolution of the carrier mode and satellites

## Experimental spectrum evolution of modulated waves



Carrier wave steepness 0.07 (without wind, from H. Branger)

## Application to Rogue Waves when modulational instability prevails

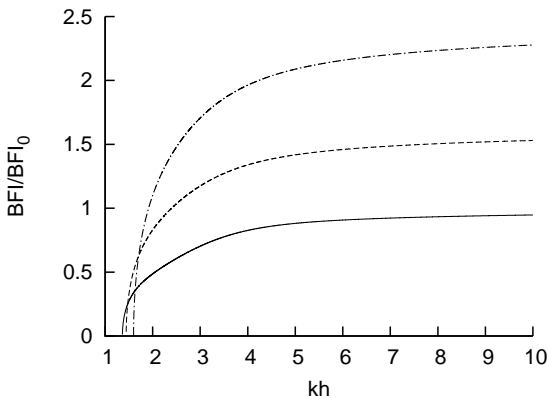
- ▶ The key parameter measuring the importance of the nonlinear four-wave interaction is the **Benjamin-Feir Index** (BFI) which is the ratio of the wave steepness to the normalized spectral bandwidth.
- ▶ Within the framework of the NLS equation the BFI writes

$$BFI = \frac{a_0 k}{\Delta K / k} \sqrt{|N_1 / L_1|}$$

where  $\Delta K$  is a typical spectral bandwidth (Onorato *et al*, 2006 and Kharif *et al*, 2009)

- ▶ The BFI is a convenient indicator for prediction of rogue wave occurrence. It is related to the pdf of wave heights. The rogue wave probability occurrence increases with the BFI.

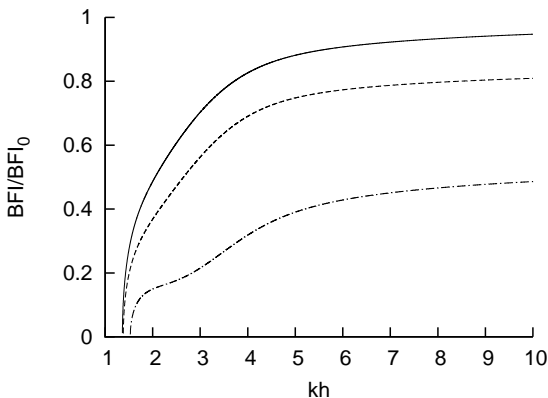
Thomas, Kharif & Manna (POF, 2012)



Normalized BFI as a function of  $kh$  for several values of  $\bar{\Omega}$ :  
 $\bar{\Omega} = 0$  (solid line),  $\bar{\Omega} = 1$  (dashed line),  $\bar{\Omega} = 2$  (dot-dashed line)



Thomas, Kharif & Manna (POF, 2012)



Normalized BFI as a function of  $kh$  for several values of  $\bar{\Omega}$ :  
 $\bar{\Omega} = 0$  (solid line),  $\bar{\Omega} = -0.3$  (dashed line),  $\bar{\Omega} = -0.6$  (dot-dashed line)

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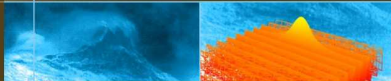
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